

The Complexity of Inferences and Explanations in Probabilistic Logic Programming

Fabio G. Cozman, Denis D. Mauá
Universidade de São Paulo

July 11, 2017

- 1 Probabilistic disjunctive logic programming.
- 2 The complexity of inferences and explanations.

Probabilistic disjunctive logic programs

- A probabilistic disjunctive logic program is a pair $\langle \mathbf{P}, \mathbf{PF} \rangle$:
 - \mathbf{P} is a disjunctive logic program (no functions) and
 - \mathbf{PF} is a set of probabilistic facts.

Probabilistic disjunctive logic programs

- A probabilistic disjunctive logic program is a pair $\langle \mathbf{P}, \mathbf{PF} \rangle$:
 - \mathbf{P} is a disjunctive logic program (no functions) and
 - \mathbf{PF} is a set of probabilistic facts.

- Predicate r , atom $r(t_1, \dots, t_k)$, rule

$$A_1 \vee \dots \vee A_h :- B_1, \dots, B_{b'}, \text{not } C_{b'+1}, \dots, \text{not } C_b$$

Probabilistic disjunctive logic programs

- A probabilistic disjunctive logic program is a pair $\langle \mathbf{P}, \mathbf{PF} \rangle$:
 - \mathbf{P} is a disjunctive logic program (no functions) and
 - \mathbf{PF} is a set of probabilistic facts.

- Predicate r , atom $r(t_1, \dots, t_k)$, rule

$$A_1 \vee \dots \vee A_h :- B_1, \dots, B_{b'}, \text{not } C_{b'+1}, \dots, \text{not } C_b$$

- A program without disjunction is *normal*.
- A program without logical variables is *propositional*.

- A probabilistic fact is a fact associated with a probability:

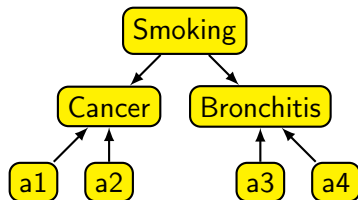
$$\mathbb{P}(A) = \alpha.$$

- Probabilistic facts are assumed independent.

Example: the Bayesian network Asia

- Predicates smoking, cancer, and bronchitis.
- Probabilistic logic program (ProbLog notation):

```
0.5 :: smoking.  
cancer :- smoking, a1.  
cancer :- not smoking, a2.  
bronchitis :- smoking, a3.  
bronchitis :- not smoking, a4.  
0.1 :: a1.      0.01 :: a2.  
0.6 :: a3.      0.3 :: a4.
```



Stratified normal programs:

- ... the grounded dependency graph has no cycle containing a *negative* edge.
- Example:

$$\begin{aligned} \text{path}(X, Y) &:- \text{edge}(X, Y). \\ \text{path}(X, Y) &:- \text{edge}(X, Z), \text{path}(Z, Y). \end{aligned}$$

Stratified normal programs:

- ... the grounded dependency graph has no cycle containing a *negative* edge.
- Example:

```
path(X, Y) :- edge(X, Y).  
path(X, Y) :- edge(X, Z), path(Z, Y).
```

```
0.6 :: edge(1, 2).  0.1 :: edge(1, 3).  
0.4 :: edge(2, 5).  0.3 :: edge(2, 6).  
0.3 :: edge(3, 4).  0.8 :: edge(4, 5).  
0.2 :: edge(5, 6).
```

- The semantics of acyclic and stratified normal programs is uncontroversial: just take the unique stable model (= answer set = well-founded model).

- The semantics of acyclic and stratified normal programs is uncontroversial: just take the unique stable model (= answer set = well-founded model).

Stable models:

- Consider logic program \mathbf{P} .
- For some interpretation \mathcal{I} , take the reduct $\mathbf{P}^{\mathcal{I}}$:
 - Ground \mathbf{P} .
 - Remove rules with subgoal **not** A and $A \in \mathcal{I}$.
 - Remove subgoals **not** A from remaining rules.
- Interpretation \mathcal{I} is stable model if \mathcal{I} is the minimal model of $\mathbf{P}^{\mathcal{I}}$.

Non-stratified program (cycle with negative edge)

- Non-stratified program may have more than one stable model.

The Dilbert example

```
single(X) :- man(X), not husband(X).
```

```
husband(X) :- man(X), not single(X).
```

```
0.9 :: man(dilbert).
```

Non-stratified program (cycle with negative edge)

- Non-stratified program may have more than one stable model.

The Dilbert example

```
single(X) :- man(X), not husband(X).
```

```
husband(X) :- man(X), not single(X).
```

```
0.9 :: man(dilbert).
```

- `man(dilbert)` is false: a unique stable model s_1 .

Non-stratified program (cycle with negative edge)

- Non-stratified program may have more than one stable model.

The Dilbert example

$\text{single}(X) :- \text{man}(X), \text{not husband}(X).$

$\text{husband}(X) :- \text{man}(X), \text{not single}(X).$

$0.9 :: \text{man}(\text{dilbert}).$

- $\text{man}(\text{dilbert})$ is false: a unique stable model s_1 .
- $\text{man}(\text{dilbert})$ is true: there are two stable models,

$s_2 = \{\text{husband}(\text{dilbert}) = \text{true}, \text{single}(\text{dilbert}) = \text{false}\},$

and

$s_3 = \{\text{husband}(\text{dilbert}) = \text{false}, \text{single}(\text{dilbert}) = \text{true}\}.$

What could be the semantics of a non-stratified program?

- Probabilities over well-founded models:
 - Sato, Kameya and Zhou (2005),
 - Hadjichristodolou and Warren (2012).
 - Riguzzi (2015).
- Proposal by Lukasiewicz (2005):
informally, take the set of every possible probability distributions that satisfy the rules and (probabilistic) facts.
 - We adopt name *credal semantics*.
 - Note: another recent semantics based on credal sets by Michels et al. (2015).

The Dilbert example

`single(X) :- man(X), not husband(X).`

`husband(X) :- man(X), not single(X).`

`0.9 :: man(dilbert).`

The Dilbert example

$\text{single}(X) :- \text{man}(X), \text{not husband}(X).$

$\text{husband}(X) :- \text{man}(X), \text{not single}(X).$

$0.9 :: \text{man}(\text{dilbert}).$

- Take any $\gamma \in [0, 1]$:

$$\mathbb{P}(s_1) = 0.1, \quad \mathbb{P}(s_2) = 0.9\gamma, \quad \mathbb{P}(s_3) = 0.9(1 - \gamma).$$

An example: robot navigation (graph coloring...)

$\text{color}(X, \text{red}) \vee \text{color}(X, \text{green}) \vee \text{color}(X, \text{yellow}) :- \text{site}(X).$

$\text{clash} :- \text{not clash}, \text{edge}(X, Y), \text{color}(X, C), \text{color}(Y, C).$

$\text{path}(X, Y) :- \text{edge}(X, Y). \quad \text{path}(X, Y) :- \text{edge}(X, Z), \text{path}(Z, Y).$

An example: robot navigation (graph coloring...)

```
color(X, red) ∨ color(X, green) ∨ color(X, yellow) :- site(X).  
clash :- not clash, edge(X, Y), color(X, C), color(Y, C).  
path(X, Y) :- edge(X, Y).    path(X, Y) :- edge(X, Z), path(Z, Y).
```

```
site(1). site(2). site(3). site(4). site(5).  
color(2, red). color(5, green).  
0.5 :: edge(4, 5).  
edge(1, 3). edge(1, 4). edge(2, 1). edge(2, 4). edge(3, 5). edge(4, 3).
```

An example: robot navigation (graph coloring...)

$\text{color}(X, \text{red}) \vee \text{color}(X, \text{green}) \vee \text{color}(X, \text{yellow}) :- \text{site}(X).$

$\text{clash} :- \text{not clash}, \text{edge}(X, Y), \text{color}(X, C), \text{color}(Y, C).$

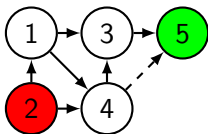
$\text{path}(X, Y) :- \text{edge}(X, Y). \quad \text{path}(X, Y) :- \text{edge}(X, Z), \text{path}(Z, Y).$

$\text{site}(1). \quad \text{site}(2). \quad \text{site}(3). \quad \text{site}(4). \quad \text{site}(5).$

$\text{color}(2, \text{red}). \quad \text{color}(5, \text{green}).$

$0.5 :: \text{edge}(4, 5).$

$\text{edge}(1, 3). \quad \text{edge}(1, 4). \quad \text{edge}(2, 1). \quad \text{edge}(2, 4). \quad \text{edge}(3, 5). \quad \text{edge}(4, 3).$



- Inference: whether $\mathbb{P}(\mathbf{Q}|\mathbf{E}) > \gamma$.

- Inference: whether $\underline{\mathbb{P}}(\mathbf{Q}|\mathbf{E}) > \gamma$.
- MPE: whether there is an interpretation \mathbf{Q} that agrees with literals \mathbf{E} , such that $\underline{\mathbb{P}}(\mathbf{Q}) > \gamma$.

- Inference: whether $\underline{\mathbb{P}}(\mathbf{Q}|\mathbf{E}) > \gamma$.
- MPE: whether there is an interpretation \mathbf{Q} that agrees with literals \mathbf{E} , such that $\underline{\mathbb{P}}(\mathbf{Q}) > \gamma$.
- MAP: whether there is a partial interpretation \mathbf{Q} that agrees with literals \mathbf{E} , such that $\underline{\mathbb{P}}(\mathbf{Q}|\mathbf{E}) > \gamma$.

Results

| | Propositional | | | Bounded arity | | |
|----------------------|---------------------------------------|--------------|------------------|---------------------------------------|--------------|------------------|
| | Inferential | MPE | MAP | Inferential | MPE | MAP |
| Acyclic normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| No negation, normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Stratified normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Normal, credal | PP ^{NP} | Σ_2^P | NP ^{PP} | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} |
| Normal, well-founded | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Disjunctive, credal | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} | PP ^{Σ_3^P} | Σ_4^P | NP ^{PP} |

(Complexity class $\Sigma_i^P = \text{NP}^{\Sigma_{i-1}^P}$.)

(Complexity class PP: class of problems solved by a probabilistic polynomial-time Turing machine.)

(In orange: PGM2016, WPLP2016, ENIAC2016.)

Results

| | Propositional | | | Bounded arity | | |
|----------------------|---------------------------------------|--------------|------------------|---------------------------------------|--------------|------------------|
| | Inferential | MPE | MAP | Inferential | MPE | MAP |
| Acyclic normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| No negation, normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Stratified normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Normal, credal | PP ^{NP} | Σ_2^P | NP ^{PP} | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} |
| Normal, well-founded | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Disjunctive, credal | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} | PP ^{Σ_3^P} | Σ_4^P | NP ^{PP} |

(Complexity class $\Sigma_i^P = \text{NP}^{\Sigma_{i-1}^P}$.)

(Complexity class PP: class of problems solved by a probabilistic polynomial-time Turing machine.)

Results

| | Propositional | | | Bounded arity | | |
|----------------------|---------------------------------------|--------------|------------------|---------------------------------------|--------------|------------------|
| | Inferential | MPE | MAP | Inferential | MPE | MAP |
| Acyclic normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| No negation, normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Stratified normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Normal, credal | PP ^{NP} | Σ_2^P | NP ^{PP} | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} |
| Normal, well-founded | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Disjunctive, credal | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} | PP ^{Σ_3^P} | Σ_4^P | NP ^{PP} |

(Complexity class $\Sigma_i^P = \text{NP}^{\Sigma_{i-1}^P}$.)

(Complexity class PP: class of problems solved by a probabilistic polynomial-time Turing machine.)

Results

| | Propositional | | | Bounded arity | | |
|----------------------|------------------|--------------|------------------|------------------|--------------|------------------|
| | Inferential | MPE | MAP | Inferential | MPE | MAP |
| Acyclic normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| No negation, normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Stratified normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Normal, credal | PP ^{NP} | Σ_2^P | NP ^{PP} | PP Σ_2^P | Σ_3^P | NP ^{PP} |
| Normal, well-founded | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Disjunctive, credal | PP Σ_2^P | Σ_3^P | NP ^{PP} | PP Σ_3^P | Σ_4^P | NP ^{PP} |

(Complexity class $\Sigma_i^P = \text{NP}^{\Sigma_{i-1}^P}$.)

(Complexity class PP: class of problems solved by a probabilistic polynomial-time Turing machine.)

Results

| | Propositional | | | Bounded arity | | |
|----------------------|---------------------------------------|--------------|------------------|---------------------------------------|--------------|------------------|
| | Inferential | MPE | MAP | Inferential | MPE | MAP |
| Acyclic normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| No negation, normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Stratified normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Normal, credal | PP ^{NP} | Σ_2^P | NP ^{PP} | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} |
| Normal, well-founded | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Disjunctive, credal | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} | PP ^{Σ_3^P} | Σ_4^P | NP ^{PP} |

(Complexity class $\Sigma_i^P = \text{NP}^{\Sigma_{i-1}^P}$.)

(Complexity class PP: class of problems solved by a probabilistic polynomial-time Turing machine.)

Results

| | Propositional | | | Bounded arity | | |
|----------------------|---------------------------------------|--------------|------------------|---------------------------------------|--------------|------------------|
| | Inferential | MPE | MAP | Inferential | MPE | MAP |
| Acyclic normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| No negation, normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Stratified normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Normal, credal | PP ^{NP} | Σ_2^P | NP ^{PP} | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} |
| Normal, well-founded | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Disjunctive, credal | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} | PP ^{Σ_3^P} | Σ_4^P | NP ^{PP} |

(Complexity class $\Sigma_i^P = \text{NP}^{\Sigma_{i-1}^P}$.)

(Complexity class PP: class of problems solved by a probabilistic polynomial-time Turing machine.)

Results

| | Propositional | | | Bounded arity | | |
|----------------------|---------------------------------------|--------------|------------------|---------------------------------------|--------------|------------------|
| | Inferential | MPE | MAP | Inferential | MPE | MAP |
| Acyclic normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| No negation, normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Stratified normal | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Normal, credal | PP ^{NP} | Σ_2^P | NP ^{PP} | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} |
| Normal, well-founded | PP | NP | NP ^{PP} | PP ^{NP} | Σ_2^P | NP ^{PP} |
| Disjunctive, credal | PP ^{Σ_2^P} | Σ_3^P | NP ^{PP} | PP ^{Σ_3^P} | Σ_4^P | NP ^{PP} |

(Complexity class $\Sigma_i^P = \text{NP}^{\Sigma_{i-1}^P}$.)

(Complexity class PP: class of problems solved by a probabilistic polynomial-time Turing machine.)

- Main goal was to map the complexity of probabilistic disjunctive logic programming (and its sub-languages) and credal and well-founded semantics.
- Future work: remove bounds on arity, and consider query complexity.

- Thanks to support by CNPq and FAPESP.