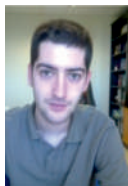


# Game solutions, probability transformations and the core

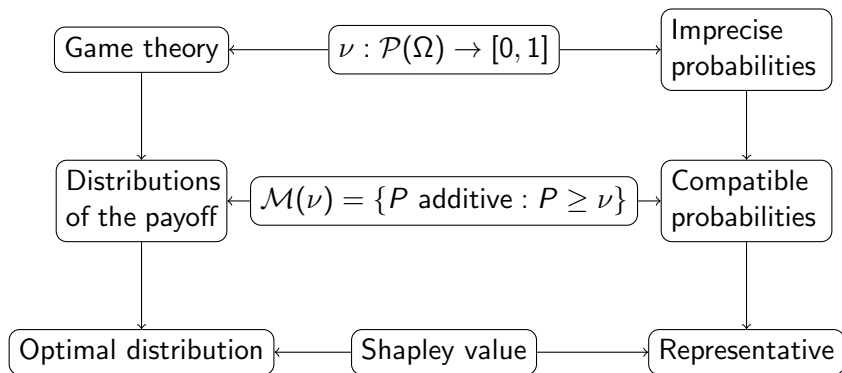
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# Summary



## Game theory with transferable utility

Consider a monotone and normalized **game** with a set of players  $\Omega$ , represented by means of a function  $\nu : \mathcal{P}(\Omega) \rightarrow [0, 1]$ .

A subset  $A \subset \Omega$  represents a **coalition** of players, and  $\nu(A)$  is the gain that is guaranteed to the players in  $A$ .

$\mathcal{M}(\nu) = \{P \text{ probability measure} : P(A) \geq \nu(A)\}$  is the set of distributions of the total payoff that cannot be improved by any coalition. It is called the **core** of the game.

We assume **transferable utility**.

## Solutions of a game

A **solution concept** of a game is a function that gives the optimal distribution of the total payoff among the players, according to some desirable properties.

The most important one is **Shapley value**, that is given by:

$$\Phi(\nu)(i) = \sum_{T \not\ni i} \frac{t!(n-t-1)!}{n!} (\nu(T \cup \{i\}) - \nu(T)),$$

where  $t = |T|$  and  $n$  is the number of players.

## Banzhaf value

Another important solution is the **Banzhaf value**:

$$B(\nu)(i) = \frac{1}{2^{n-1}} \sum_{T \not\ni i} \nu(T \cup \{i\}) - \nu(T).$$

Unlike Shapley value, this solution is not normalized: we may have  $\sum_i B(\nu)(i) \neq 1$ . This led **van der Brink and van der Laan** to propose the **normalized Banzhaf value**:

$$\Psi(\nu)(i) = \frac{B(\nu)(i)}{\sum_j B(\nu)(j)}.$$

## Imprecise probabilities

In imprecise probability theory, we can consider a random variable  $X$  with values in a set  $\Omega$ . Then we regard  $\nu : \mathcal{P}(\Omega) \rightarrow [0, 1]$  as a model for the imprecise knowledge for the distribution of  $X$ .

Then  $\nu(A)$  is a lower bound for the probability that  $X$  takes a value in  $A$ , and  $\mathcal{M}(\nu) = \{P \text{ probability measure} : P(A) \geq \nu(A)\}$  would be the set of probabilities that are compatible with the available information.

Depending on the properties  $\nu$  satisfies, we talk of different types of **imprecise probability models**.

## Connection game theory $\leftrightarrow$ imprecise probabilities

**Shapley** showed that, when  $\nu$  is **convex** (=2-monotone)

$$\nu(A \cup B) + \nu(A \cap B) \geq \nu(A) + \nu(B) \quad \forall A, B,$$

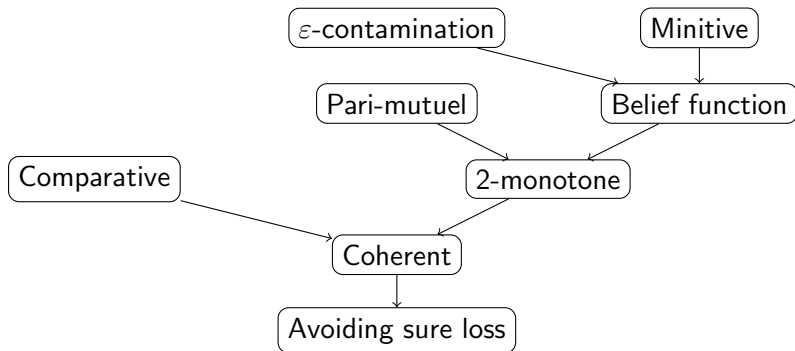
Shapley value coincides with the **center of gravity** of  $\mathcal{M}(\nu)$ .

Thus,  $\Phi(\nu)$  is the average of the extreme points of  $\mathcal{M}(\nu)$ , and this implies that it coincides with the **pignistic transformation** of  $\nu$ , proposed among others by **Smets**.

This connects game solutions with the problem of **probability transformations**: transforming a IP model  $\nu$  into a representing probability measure in  $\mathcal{M}(\nu)$ .

## Relationships between the IP models

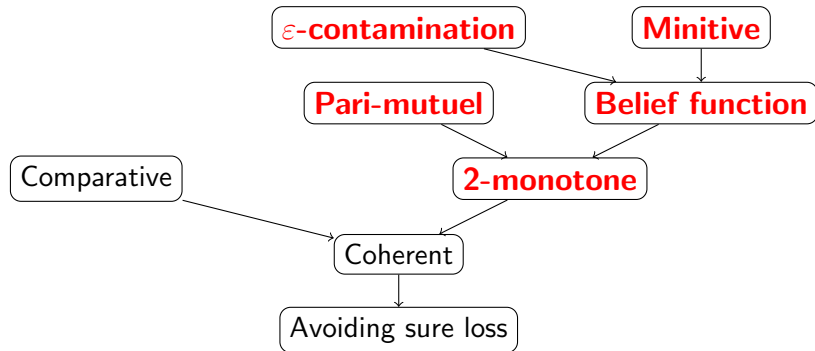
We investigate the role of Shapley and Banzhaf values as probability transformations for a number of different IP models:





## Particular cases of 2-monotone games

First we consider a number of particular cases of 2-monotone capacities:



## Belief functions

A 2-monotone capacity is a **belief function** when its Möbius inverse  $m$  is non-negative.

- ▶  $\Psi(\nu)$  need not belong to  $\mathcal{M}(\nu)$ .
- ▶ When  $\nu$  is the **unanimity game** on  $S$ ,  $\nu(A) = \begin{cases} 1 & \text{if } S \subseteq A \\ 0 & \text{otherwise} \end{cases}$ ,  
 we have that  $\Phi(\nu) = \Psi(\nu)$  is the uniform distribution on  $S$ .

Two particular cases of belief functions are *minitive measures* and  *$\varepsilon$ -contamination models*.

## Minitive measures

$\nu$  is **minitive** when  $\nu(A \cap B) = \min\{\nu(A), \nu(B)\} \forall A, B \subseteq \mathcal{X}$ .

- ▶  $\Phi(\nu)(i) = \sum_{j=i}^n \frac{m(\{1, \dots, j\})}{j} \quad \forall i$  (Dubois and Prade).
- ▶  $\Psi(\nu)(i) = \frac{\sum_{j=i}^n 2^{n-j} m(\{1, \dots, j\})}{\sum_{j=1}^n j \cdot 2^{n-j} m(\{1, \dots, j\})} \quad \forall i$ .
- ▶  $\sum_i B(\nu)(i) \leq 1$ .

## $\varepsilon$ -contamination models

Given a probability measure  $P_0$  and  $\varepsilon \in (0, 1)$ , the  $\varepsilon$ -contamination model they induce is

$$\nu(A) = (1 - \varepsilon)P_0(A) + \varepsilon\nu_\Omega(A),$$

where  $\nu_\Omega(A) = 0$  unless  $A = \Omega$  (the unanimity game on  $\Omega$ ).

- ▶  $\Phi(\nu)(i) = (1 - \varepsilon)P_0(\{i\}) + \frac{\varepsilon}{n} \forall i.$
- ▶  $\Psi(\nu)(i) = \frac{(1-\varepsilon)P_0(\{i\}) + \frac{\varepsilon}{2^{n-1}}}{k}$ , where  $k = (1 - \varepsilon) + \frac{n\varepsilon}{2^{n-1}}.$
- ▶  $\Phi(\nu), \Psi(\nu) \in \mathcal{M}(\nu).$
- ▶  $\Phi(\nu) = P_0 \iff \Psi(\nu) = P_0 \iff P_0$  uniform.

## Pari mutuel models

Given a probability measure  $P_0$  and a distorsion value  $\delta > 0$ , the **pari-mutuel model** they induce is

$$\nu(A) = \max\{(1 + \delta)P_0(A) - \delta, 0\}.$$

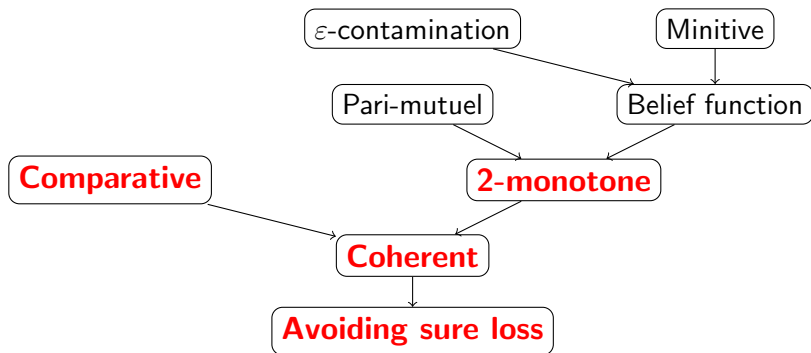
It is 2-monotone, but not necessarily a belief function.

If  $\delta < \min_i \frac{P_0(\{i\})}{1 - P_0(\{i\})}$ , then:

- ▶  $\Phi(\nu)(i) = (1 + \delta)P_0(\{i\}) - \frac{\delta}{n} \quad \forall i.$
- ▶  $\Psi(\nu)(i) = \frac{(1+\delta)P_0(\{i\}) - \frac{\delta}{2^{n-1}}}{k}$ , where  $k = (1 + \delta) - \frac{n\delta}{2^{n-1}}.$
- ▶  $\Phi(\nu), \Psi(\nu) \in \mathcal{M}(\nu).$
- ▶  $\Phi(\nu) = P_0 \iff \Psi(\nu) = P_0 \iff P_0 \text{ uniform.}$

## More general models

We consider next models that are not 2-monotone in general:



## Coherent lower probabilities

$\nu$  is **coherent**  $\iff \nu(A) = \min\{P(A) : P \in \mathcal{M}(\nu)\} \forall A$ . They correspond to **exact** games.

- ▶  $\nu = \min\{P_1, P_2\} \Rightarrow \Phi(\nu) = \Psi(\nu) = (P_1 + P_2)/2$ .
- ▶  $|\Omega| = 4 \Rightarrow \Phi(\nu) \in \mathcal{M}(\nu)$ , but  $\Psi(\nu)$  need not belong to  $\mathcal{M}(\nu)$ .
- ▶  $|\Omega| = 5 \not\Rightarrow \Phi(\nu) \in \mathcal{M}(\nu)$  (**Baroni and Vicig**).

## Comparative probabilities

Let  $\mathcal{I} \subseteq \Omega \times \Omega$ . The (elementary) **comparative model** determined by  $\mathcal{I}$  is the lower envelope  $\underline{P}$  of the set

$$\mathcal{M} := \{P \text{ probability measure} : P(\{i\}) \geq P(\{j\}) \forall (i, j) \in \mathcal{I}\}.$$

It determines a coherent lower probability, but not necessarily a 2-mononote one.

- ▶  $\Phi(\nu), \Psi(\nu) \in \mathcal{M}(\nu)$ .
- ▶  $\Phi(\nu)$  need not coincide with the center of gravity of  $\mathcal{M}(\nu)$ .



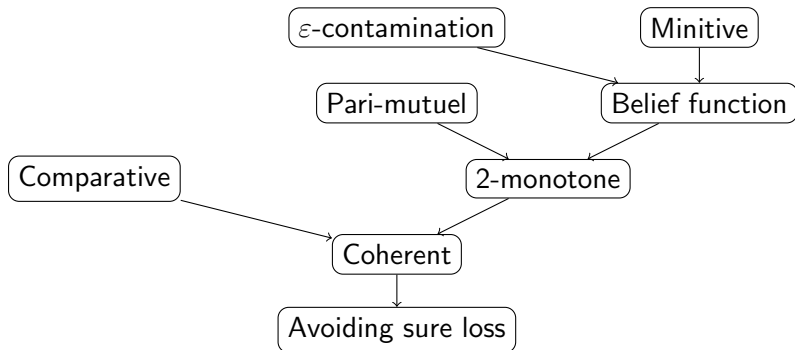
## Lower probabilities avoiding sure loss

We say that  $\nu$  **avoids sure loss** when  $\mathcal{M}(\nu) \neq \emptyset$ . They correspond to **balanced** games.

If  $\nu$  is coherent, then it avoids sure loss, but the converse is not true.

- ▶  $\nu$  avoids sure loss  $\not\Rightarrow \Phi(\nu), \Psi(\nu) \in \mathcal{M}(\nu)$ , not even with  $|\mathcal{X}| = 3$ .

## Relationships between the IP models



## Summary of the results

$\nu$	$\Phi(\nu)$ $\in \mathcal{M}(\nu)$ ?	$\Psi(\nu)$ $\in \mathcal{M}(\nu)$ ?	$\Phi(\nu)$ center of $\mathcal{M}(\nu)$ ?	$\sum_i B(\nu)(i) \leq 1$ ?
ASL	NO	NO	NO	NO
Coherent, $ \Omega  \leq 3$	YES	YES	YES	NO
Coherent, $ \Omega  \leq 4$	YES	NO	NO	NO
Comparative Coherent	YES NO	YES NO	NO NO	NO NO
Pari-mutuel	YES	YES	YES	NO
2-monotone	YES	NO	YES	NO
Belief	YES	NO	YES	YES
Minitive	YES	YES	YES	YES

## Open problems

- Study of other IP models: probability intervals,  $p$ -boxes.
- Comparison with other probability transformations.
- Do Shapley and Banzhaf satisfy desirable properties of probability transformations?
- Translation of desirable properties of game solutions into the context of imprecise probabilities.

## References

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- P. Smets, *Decision making in the TBM: the necessity of the pignistic transformation*. Int. J. of Approximate Reasoning, 2005.
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Thank you for your attention!

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